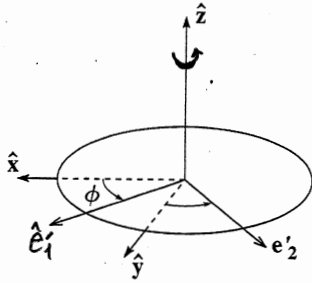
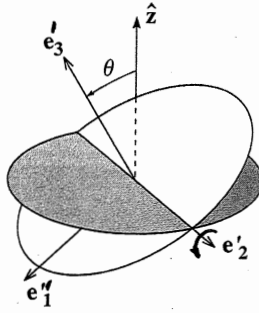


# Euler angles:

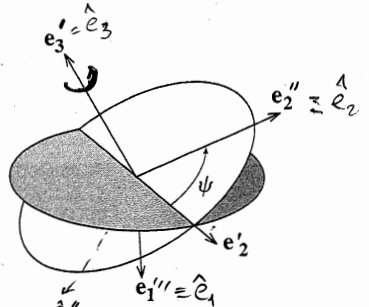
zyz active rotation



(a)



(b)



(c)

